## SOLUTIONS TO TUTORIAL EXAMPLES

CHAPTER 11

The symbols used in the table below are the same as those used in Chapter 11, as follows:
$\mathrm{m}=$ number of members
$\mathrm{j}=$ number of joints
$r=$ number of restraints
For each roller support $\mathrm{r}=1$
For each pinned support $\mathrm{r}=2$
For each fixed support $r=3$
SD = statically determinate
$\mathrm{SI}=$ statically indeterminate (contains redundant members)
Mech = a mechanism (unstable)
> means 'greater than'
< means 'less than' (standard mathematical symbols)

|  | m | j | 2 j | r | $\mathrm{m}+\mathrm{r}$ | Is $(\mathrm{m}+\mathrm{r})$ <br> $=2 \mathrm{j} ?$ | Stability <br> Type |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Question 1 | 8 | 6 | 12 | 4 | 12 | $=$ | SD |
| Question 2 | 7 | 5 | 10 | 3 | 10 | $=$ | SD |
| Question 3 | 6 | 4 | 8 | 3 | 9 | $>$ | SI |
| Question 4 | 14 | 9 | 18 | 4 | 18 | $=$ | SD |
| Question 5 | 12 | 8 | 16 | 3 | 15 | $<$ | Mech |

In Question 3, any one member could be removed and the frame would still be stable.

In Question 5, a diagonal member BG or HE would ensure stability.

